



# From Waste Chaos to Compliance: A Robotic AI System Achieving Real-World Remediation End States



## **About Us**

- Research & Development
- Founded in 2008
- Privately Owned
- Headquarters in the United Kingdom
- Offices in Japan, United States and South Korea





## Sort & Segregation of Nuclear Waste

#### **Automation of Nuclear Waste Sorting**

Utilises advanced computer vision, ML and robotic technology

#### **Identifies Waste**

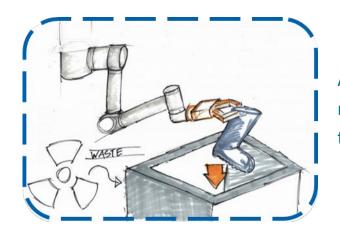
Identifies and sorts debris based on size, material and shape

#### **Agnostic Platform**

Utilised by any robotic platform



Humans assess and sort contaminated into the appropriate stream for disposal.



A robot can mimic human activity via machine learning and allocate the waste to the appropriate stream.



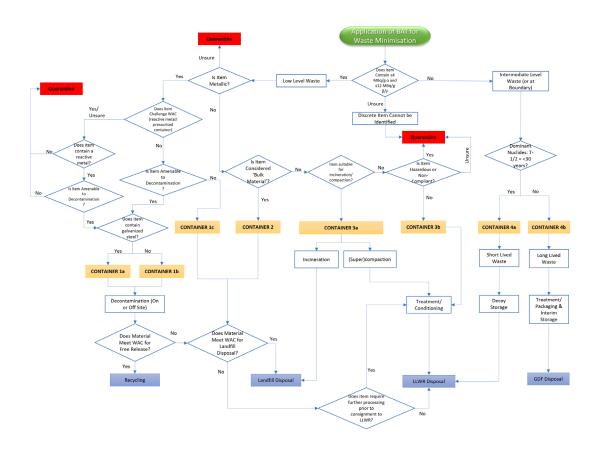
## Waste Stream Compliance

#### BAT – Best Available Technique

- Utilise the best practical methods currently available.
- That are technically and economically feasible.
- And that minimised the generation of waste or its hazardous properties.

#### Relevance to UK and EU Nuclear Regulation.

 Operators are required to demonstrate the application of BAT when managing radioactive or hazardous waste.





## **Material Identification**

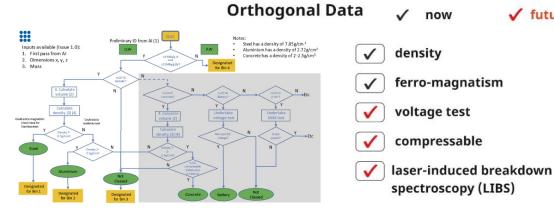
- Initial identification via Machine Learning (deep-learning computer vision).
- Orthogonal datasets for mass and paramagnetic materials.
- Laser ablation techniques
- Hyperspectral imaging techniques

#### Material identification

## **Initial Recognition** Deep learning recognition



√ future





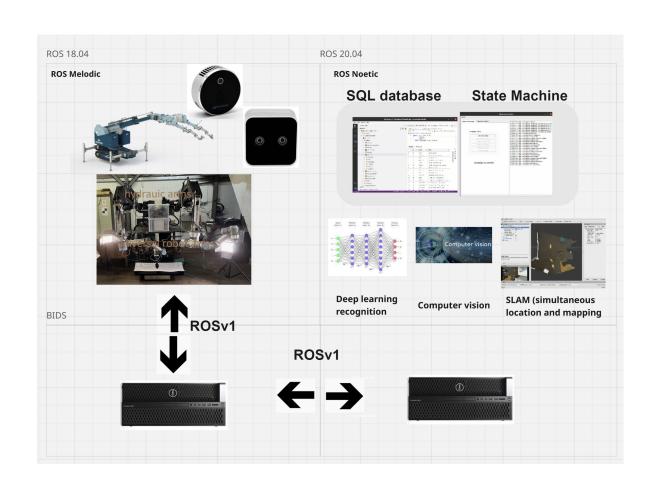
## System Architecture

#### Device side (ROS Melodic):

 Interfaces to hydraulic arms/universal robots, RGB-D cameras, and other sensors provide real-time motion control.

#### Perception (ROS Noetic):

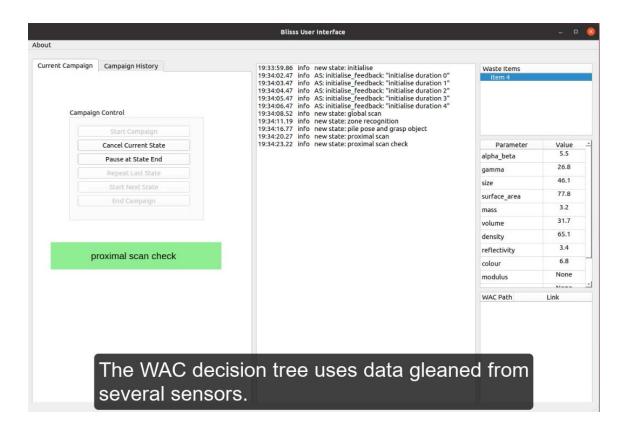
- Deep-learning recognition for object/material ID.
- Computer vision for pose detection.
- SLAM for workspace mapping and localisation.
- State machine coordinates tasks, exceptions, and recovery sequences.
- SQL database logs images, features, decisions, and traceability metadata.





### Waste Item Process

- Example of waste classification
- Each stage of the identification
- Laser ablation tec
- Hyperspectral imaging techniques





## **Waste Allocation**

- Follows the WAC Decision Tree
- Classifies: material, radiological Identification (iso
  ID) & object ID (shoe/tool/parts, etc)
- Routes to correct assignment
- Packing
- An image of the item placed in the correct bin is in the SQL database.



## Auto Allocation of Nuclear Waste: Summary

- **Problem:** Manual waste sorting is variable, slow, and dose-intensive with limited traceability.
- **Principle:** Decisions are grounded in BAT—best practical, technically & economically feasible methods that minimise waste and hazard.
- **Solution:** Automated sort & segregation using computer vision + ML + robotics, aligned to site WAC/BAT rules with quarantine for uncertainty.
- Material ID: Fast DL recognition, then orthogonal tests (density, magnetism, voltage, compressibility; roadmap: LIBS, hyperspectral) to raise confidence and auditability.
- **Value:** Lower dose (ALARP), higher throughput, fewer mis-sorts, increased recycling/decontamination, strong compliance evidence.



