

#### Physics-Informed Surrogate Modeling for Supporting Climate Resilience at Groundwater Contamination Sites

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### Changing climate on groundwater contamination sites

Extreme precipitation and increased recharge



with wastewater



# Bridging the gap between science and decision with machine learning (ML)

Where and when to make remediations? Put monitoring wells?



## Slow and uncertain: Flow and transport simulations with climate models



An SRNS subcontractor technician takes radiological readings of soil near Lower Three Runs, part of a major project to complete the cleanup of a contaminated 25-mile-long stream corridor at SRS. (Photo: DOE)

# Fast and high risk: Design attenuation strategies under climate disturbances

#### **Physics-informed surrogate modeling**



**Wang** et al. 2022, Machine Learning and the Physical Sciences workshop, NeurIPS Meray\*, **Wang**\* et al. 2023, Computers and Geosciences, under review

#### Surrogate modeling: Input and Output

#### Input parameters m(x,t): permeability, porosity, recharge, location, time, etc. $n_x \times n_z \times n_t \times n_{input}$



<u>Output parameters y(x,t)</u>: tritium concentration, hydraulic head  $n_x \times n_z \times n_t \times n_{output}$ 

#### **Surrogate modeling: Fourier Neural Operator**



Step 1: Fourier transform  $\mathcal{F}$ 

Step 2: Linear transform on the lower Fourier modes R

Step 3: Inverse Fourier transform  $\mathcal{F}^{-1}$ 

Li et al. 2021, Wen et al. 2022

#### Surrogate modeling: Fourier Neural Operator + U-Net



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Step 3: Inverse Fourier transform  $\mathcal{F}^{-1}$ 

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#### Surrogate modeling: two different architectures

a)



#### Surrogate modeling: Physics-informed loss function

$$\mathcal{L}(y, \hat{y}) = \mathcal{L}_{MRE}(y, \hat{y}) + eta_1 \mathcal{L}_{der}(y, \hat{y}) + eta_2 \mathcal{L}_{plume}(c', \hat{c'}) + eta_3 \mathcal{L}_{BC}(\hat{y})$$

Simulated data-driven: Mean relative error on output and corresponding derivatives

$${\mathcal L}_{MRE}(y,\hat{y}) = rac{\|y-\hat{y}\|_2}{\|y\|_2} \ \ {\mathcal L}_{der}(y,\hat{y}) = rac{\|\partial y/\partial x-\partial \hat{y}/\partial x\|_2}{\|\partial y/\partial x\|_2} + rac{\|\partial y/\partial z-\partial \hat{y}/\partial z\|_2}{\|\partial y/\partial z\|_2}$$



Simulated data-driven: Derivatives on the plume boundary

$$\mathcal{L}_{plume}(c',\hat{c'}) = rac{\|\partial c'/\partial x - \partial \hat{c'}/\partial x\|_2}{\|\partial c'/\partial x\|_2} + rac{\|\partial c'/\partial z - \partial \hat{c'}/\partial z\|_2}{\|\partial c'/\partial z\|_2}$$

Physics-informed: No flow boundary condition for hydraulic head

$$\mathcal{L}_{BC}(\hat{y}) = \|\hat{q}_x|_{\partial D}\|_2 + \|\hat{q}_z|_{\partial D}\|_2 + \|\partial\hat{h}|_{\partial D}\|_2$$



#### **Tritium concentration on test set**

Physics-informed surrogate model runs 600x faster than Amanzi-ATS



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#### **Performance: multiple loss functions**

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#### **Performance: multiple different architectures**

#### With 30 epochs



#### **Performance: multiple different architectures**

With 150 epochs



#### **Architecture for future projections**



#### **Architecture for future projections**



#### Conclusion

- We propose two different architectures U-FNO-2D (recurrent) and U-FNO-3D.
- We design the custom loss functions including:
  - Simulated data-driven loss
  - Physics-informed loss
- U-FNO-3D has more parameters for better training and predictions
- U-FNO-2D is well-suited for predicting the future climate perturbation impacts

#### Future surrogate modeling with full 3D model



#### What is next?

Integrate in-situ long-term monitoring data and support remediation decisions

